Plans for Extending COGENT to Model Snowflake Divertors

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ESL Team Meeting, GA, Sept 30-Oct 1, 2014

This work was performed for USDOE, at LLNL under contract DE-AC52-07NA27344, at CompX under sub-contract from LLNL, and at LBNL under contract DE-AC02-05CH11231

OUTLINE

- What and why of snowflake divertors
- Exact versus approximate snowflake divertors
- Objectives for modeling snowflakes with COGENT
- COGENT gridding strategy for conventional divertor tokamaks
- Strategy for extension to snowflakes: simple!
- First step: model and test local region about poloidal field null

Snowflake divertors: What and Why

- What: Extra coil(s) to produce 2nd-order null instead of usual (1st-order) x ٠ point in SOL. 0.5 0.5 x
- Why:
 - Primary benefit, spreading of heat load via increased flux expansion.
 - Secondary benefits: further spreading among multiple divertor legs via MHD convection
 - Further isolation of main SOL and divertor legs RE instabilities (increased shear)
 - Other benefits, e.g. reduced peak heat load during ELMs

Exact versus approximate snowflake divertors

- Exact snowflake: perfect tuning of coils to achieve 2nd-order null
- Structurally unstable: if one of the coils has current a bit too high or low, the 2nd-order null splits into 2 nearby 1st-order nulls
- Snowflake plus:







- Above examples are symmetric approximate snowflakes. They needn't be. e.g.:
- If the 1st-order nulls are close enough, macroscopic behavior mostly indistinguishable from exact snowflake.



Objectives for modeling snowflakes with COGENT

- Snowflake divertors are getting a lot of attention at DIII-D and elsewhere, need to model them.
- Initial objectives similar to those for conventional divertors:
 - Neoclassically driven flows and radial transport in presence of divertor losses
 - Distribution of collision-driven losses to divertor plates
- Have divertor geometry in the mix as COGENT capability is expanded (e.g. to include 5-D physics)

COGENT gridding strategy for conventional divertors: abandon field-line following near x point

- When the divertor version of COGENT was first developed it was noted that the nominally 4th-order discretization was yielding results for advection converging more slowly than $(\Delta x)^4$
 - Explanation: curvature, metrics becoming singular as x point is approached.
- Solution: Gridding that follows flux surfaces away from x point but departs so as to preserve smoothness near x point
 - Flows near x point not flux-surface-following anyway
 - Use 4th-order interpolation to fill ghost cells



Strategy for extension to snowflakes: simple!

 Implication of extrapolated grid strategy for snowflake divertor: Since field-line following is abandoned anyway, a single grid structure generated for an exact snowflake divertor geometry is likely to work for nearby approximate snowflakes

First step: model local region about poloidal field null

- Ryutov et al PPCF '08: cubic expansion of flux surface about null.
 - Neglecting current near null, have flux function

 $\Phi = l_1 x + l_2 z - q_3 x^2 + 2q_2 xz + q_3 z^2 + c_1 x^3 - 3c_4 x^2 z - 3c_1 xz^2 + c_4 z^3$ - And fields

$$-(R+x)B_{x} = l_{2} + 2q_{2}x + 2q_{3}z - 3c_{4}(x^{2} - z^{2}) - 6c_{1}xz,$$

$$(R+x)B_{z} = l_{1} - 2q_{3}x + 2q_{2}z + 3c_{1}(x^{2} - z^{2}) - 6c_{4}xz.$$

- With suitable choices of coefficients, can make exact snowflake and approximate snowflakes
- Strategy:
 - Starting from exact snowflake coefficients, generate extrapolated grid as discussed above
 - Do runs with B on this grid evaluated for exact and approximate snowflakes, compare physics results (next slide)

REMARKS

- Will use grid generator developed by P. Schwartz, which does leastsquares optimization of grid smoothness and field line following with weights that vary with field-line curvature
- Initial testing with pure advection (no collisions): Initiate (half) Maxwellian in main SOL; predictable difference of fluxes on various divertor plates depending on type of approximate snowflake



• Subsequent studies: add collisions (neoclassical); add model of MHD convective mixing near null; full SOL. Compare with analytic models that may be available, and with experiments